Ghost Mesh: Cloud-Based Interactive Mesh Editing

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Outline

- Ghost Mesh System Pipeline
- User Interface
- Algorithms
- Evaluation
- Editing Examples

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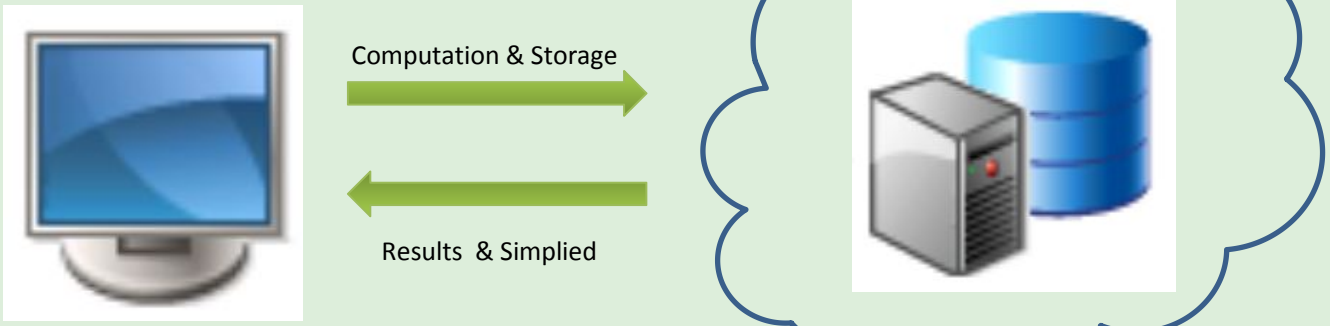
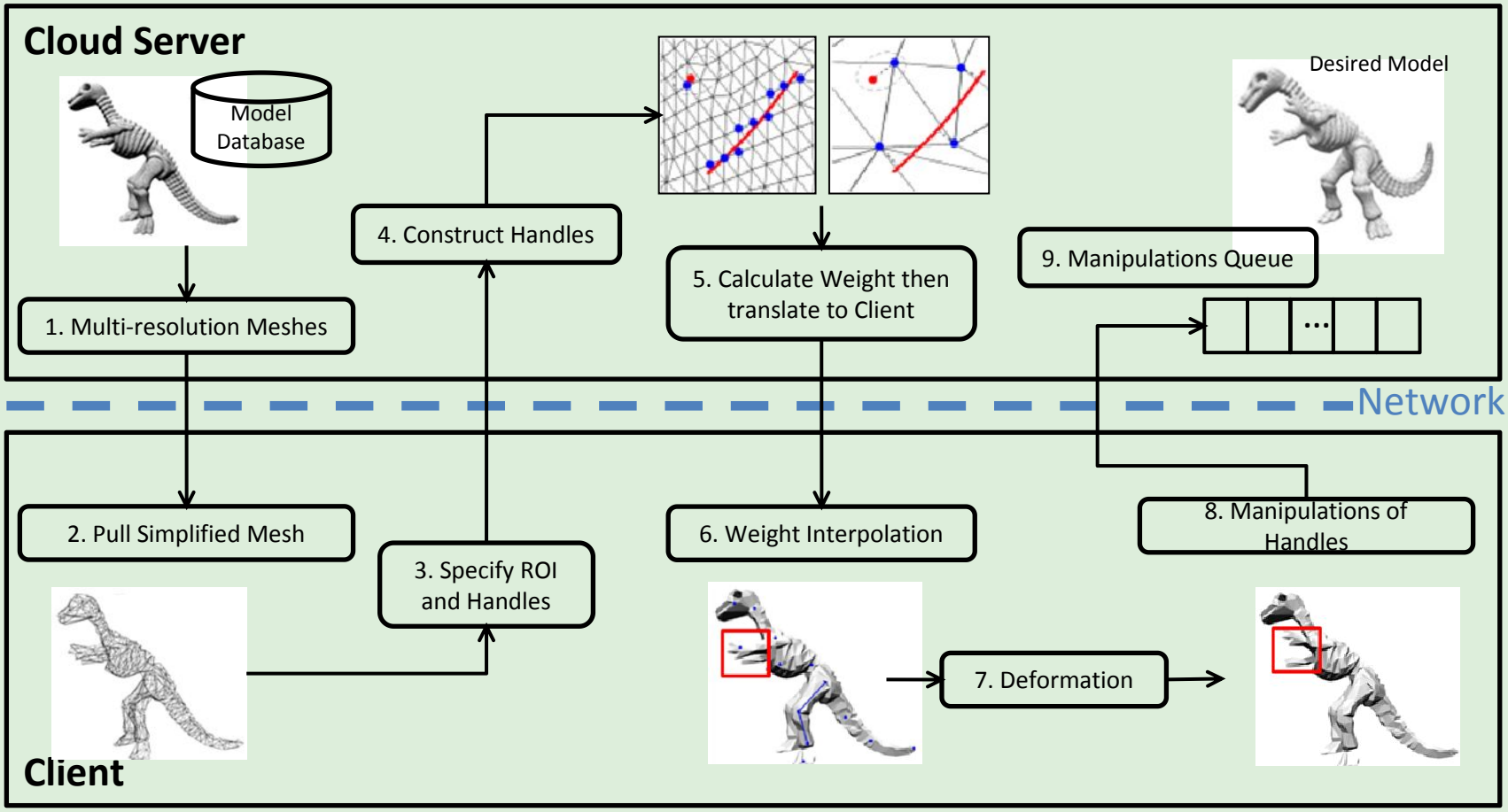
Cloud Based

- Effective interactive deformation of complex objects requires:
  - High computation capability
  - Large storage resources
- So …



System Pipeline



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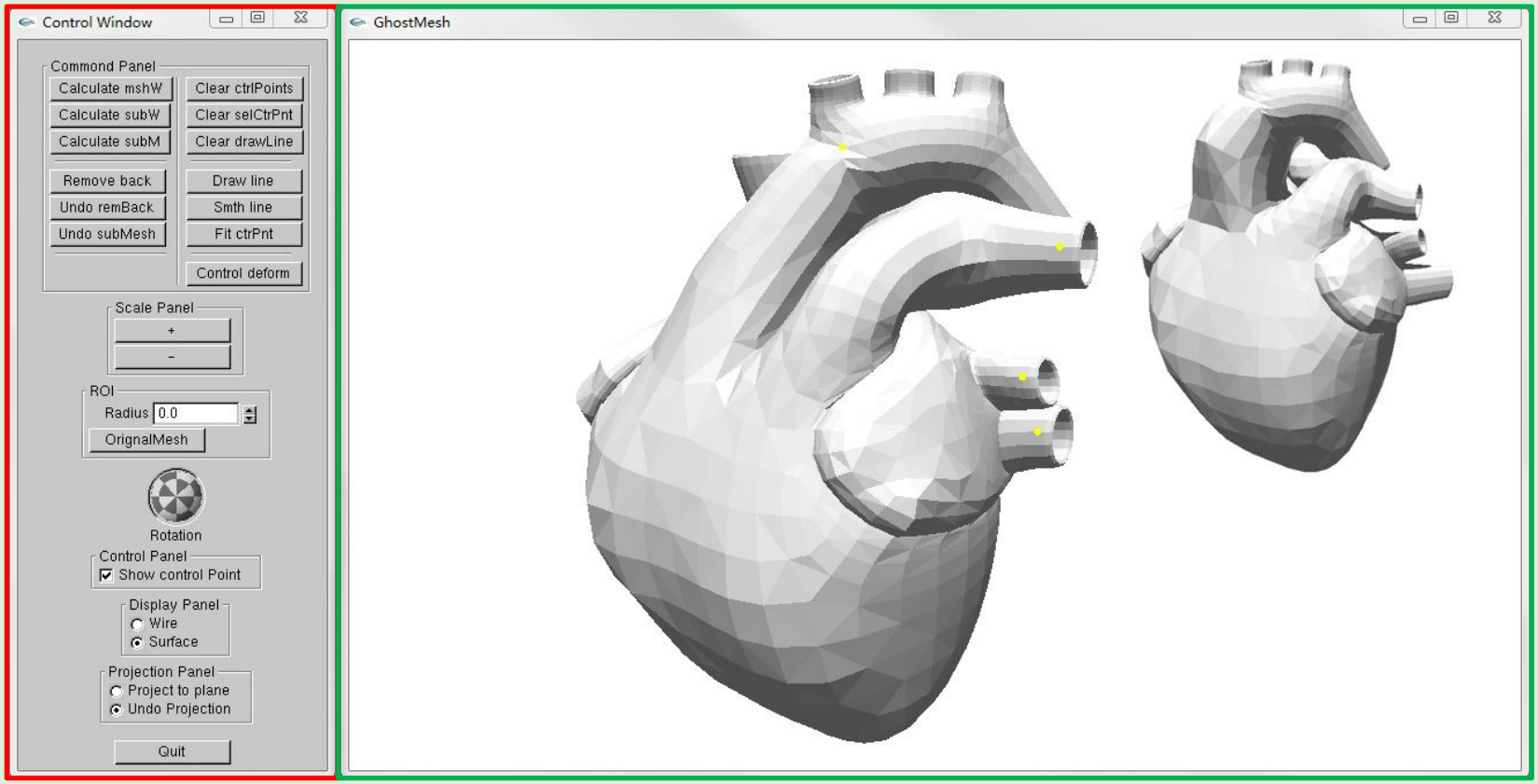
User Interface(1)

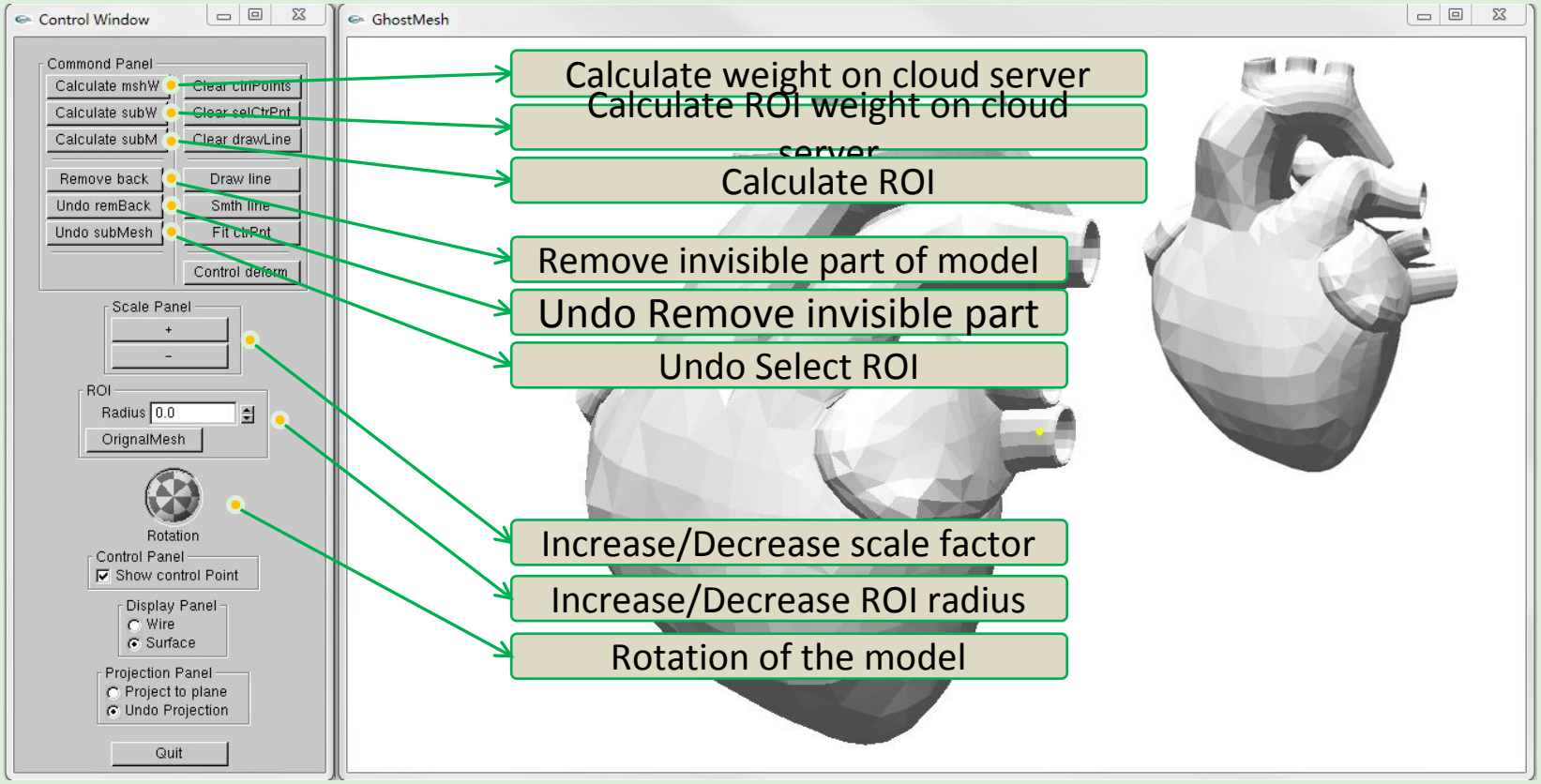
Button panel

Rendering window



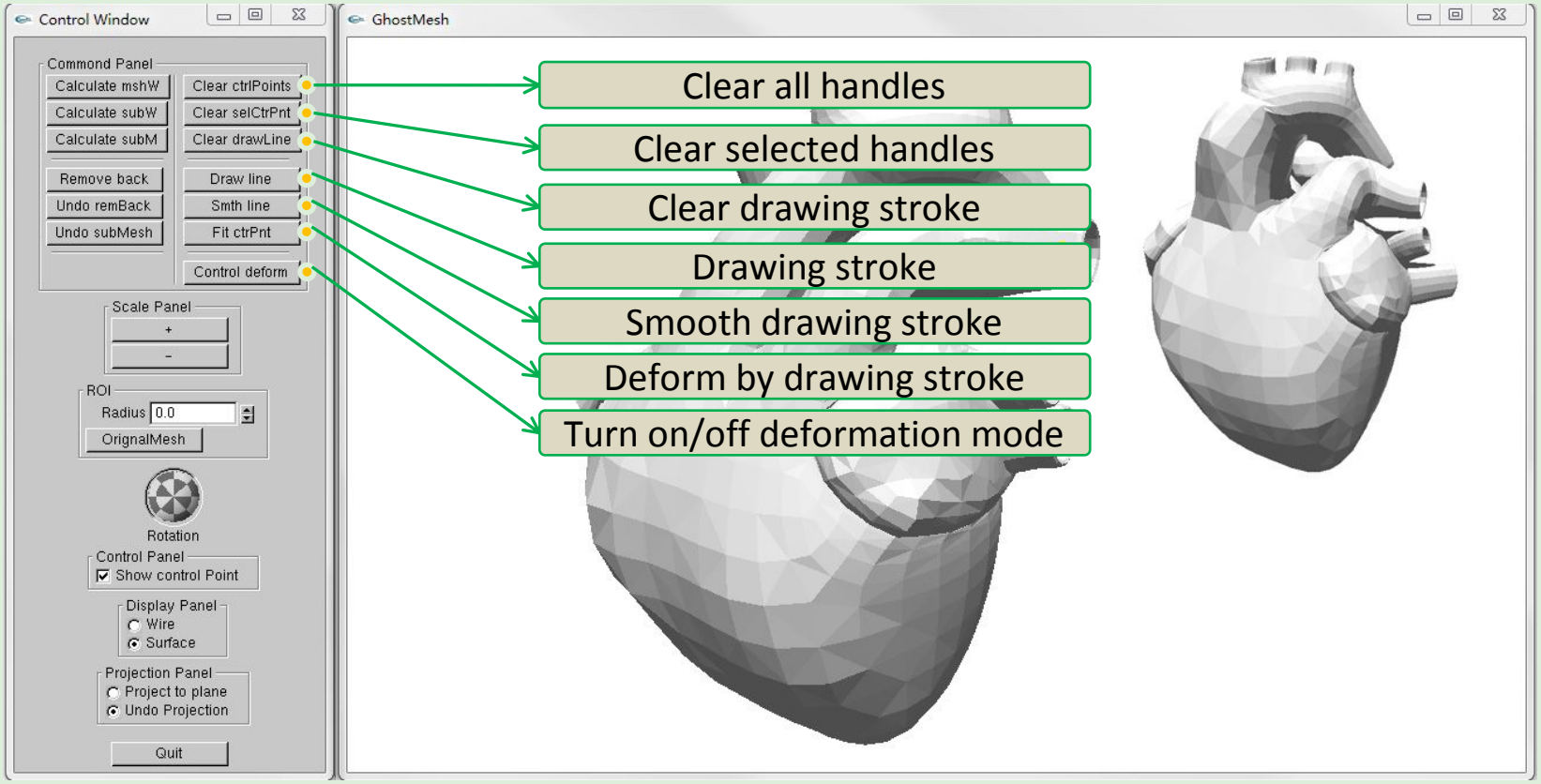
Ghost Mesh user interface

User Interface(2)



Ghost Mesh user interface

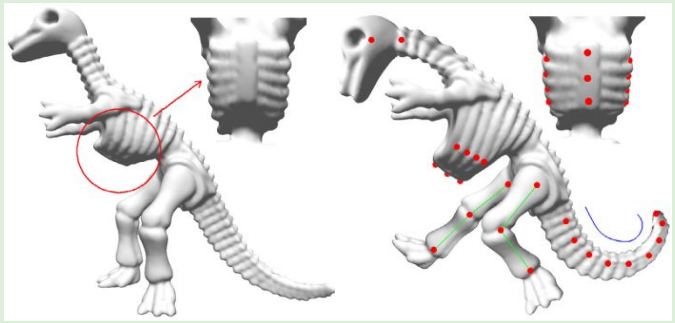
User Interface(3)

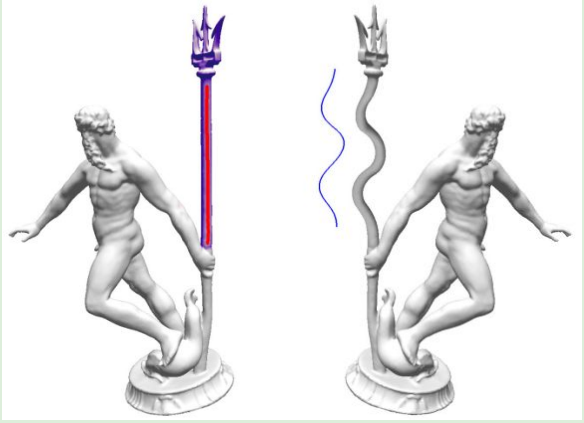


Ghost Mesh user interface

Handle Tool and ROI Tool

- Clicks or drags on the simplified surface to specify a number of handles.





- Point handle
  - Translation, scale, rotation
- Skeleton handle
  - Drag
- Control curve handle
  - Define desired deformation
- ROI tool
  - Specify ROI

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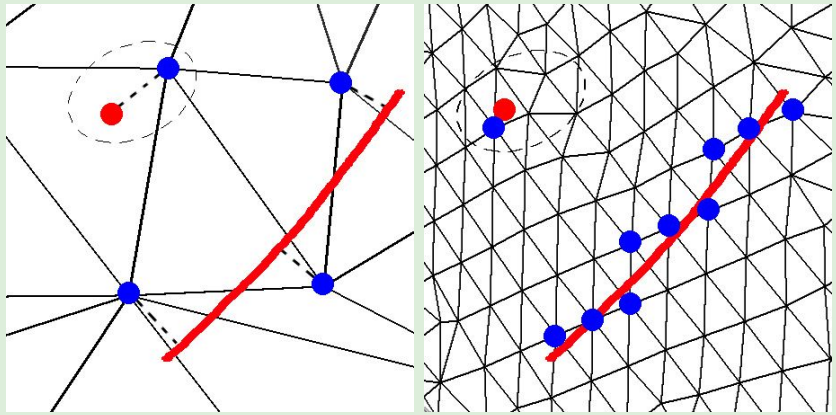
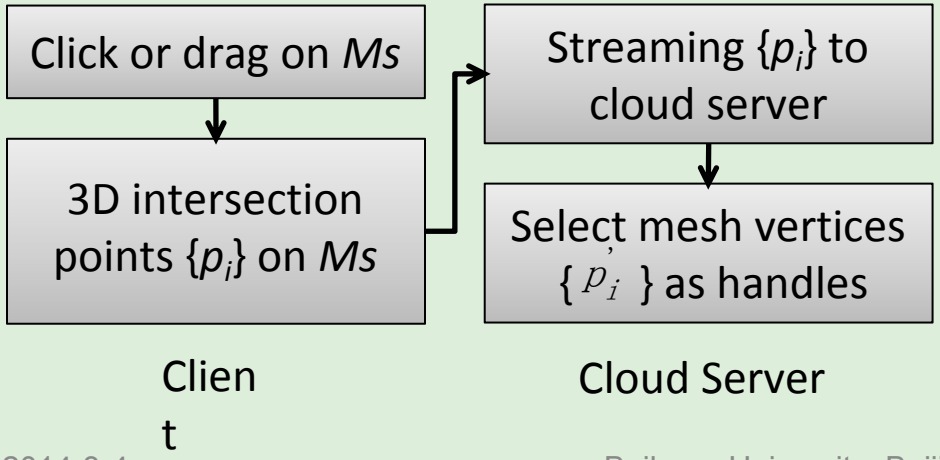
Algorithms

- Handle Selection and Optimization
- Weight Computing
- Data Transmission

Handle Selection and Optimization



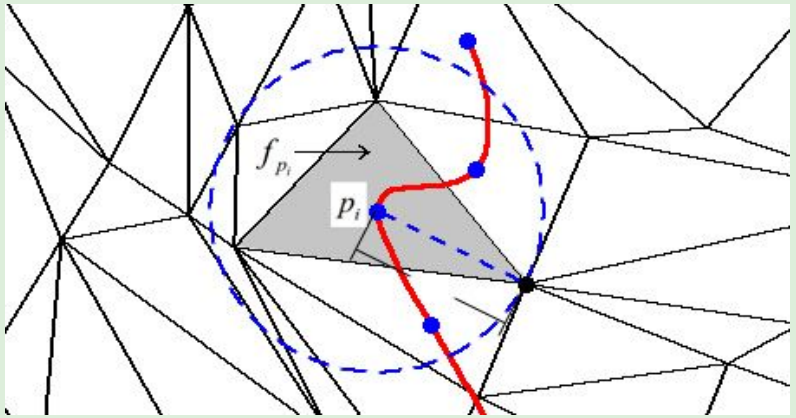
Comparison between simplified and original surface



- In current implementation we choose some of the mesh vertices as handle members.
- It is obvious that handles constructed on the original complex mesh are more close to the user intention.
- When the user picks 3D points on the simplified mesh *Ms*, the system streams these points to the cloud server, constructing handles on the complex surface.

Select mesh vertices as handles

$$L = \{p_i \mid \text{intersection points on Ms}\} \xrightarrow{\text{construct}} L' = \{p_i' \mid p_i' \in V\}$$



Initial parameters of collecting p_i'

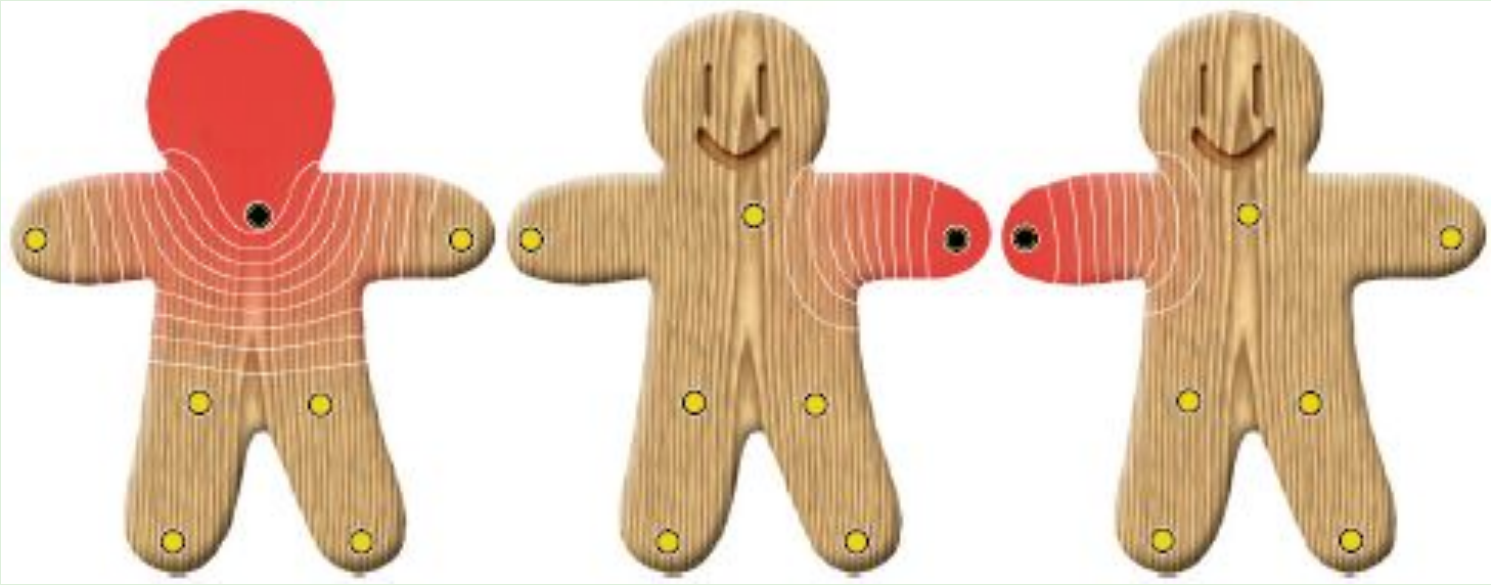
Subject to $\arg\min_{p_i', i=1,\ldots,m} \sum_{i=1}^{m} \sum_{p_j \in N(i)} \| p_i' - p_j \|_2$

In practice, we compute the new line L' by collecting new point p'_i through a flood filling process performed on original mesh M, starting at the first vertex of face f(p_i) and restricted to the euclidean distance from it to p_i

- m : is the size of set L = {p_i}
- *N(i)* : is the set of p_i and its neighbors in L

Weight Computing

- Computed by powerful cloud server
- Use BBW [1] for computing weight



1. [Jacobson A, et al. SIGGRAPH 11]

Data Transmission

Data transmission includes:

- Progressive meshes
- Creation of handles
- ROI parameters
- Blending weights
- Manipulations of handles

Manipulations Transmission

Simplified Mesh on Client

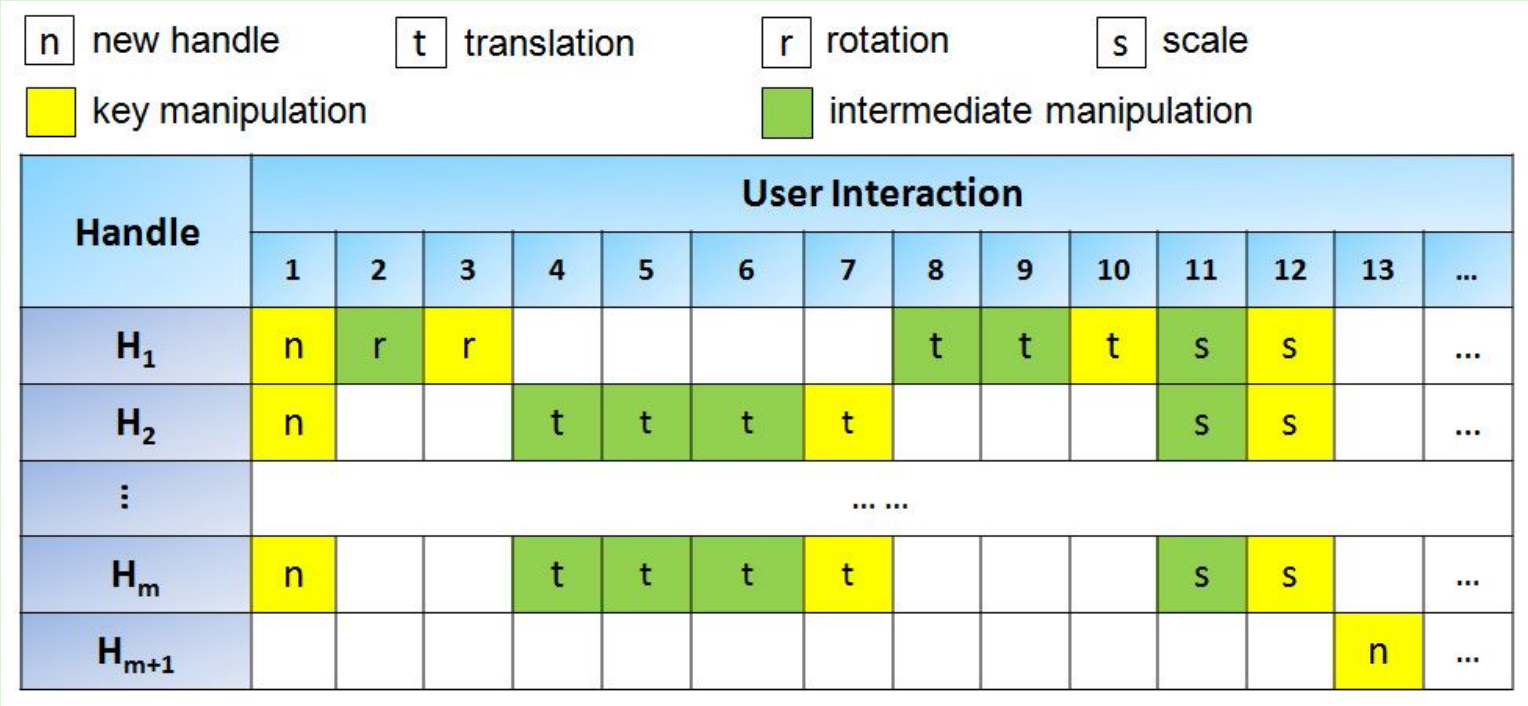
User Manipulations

- Intermediate manipulations
- Key manipulations

Original Mesh on Server

- Two cases producing Intermediate manipulations
  - Specifying a same kind of manipulation(i.e., T., R., S.) *multiple time* to get a desired deformation
  - System records continuous changes of handles by just one user manipulation, such as the trajectory of moving a point by dragging
- Key manipulations
  - Final result of a series of intermediate manipulations
  - A single manipulation

Manipulations Transmission

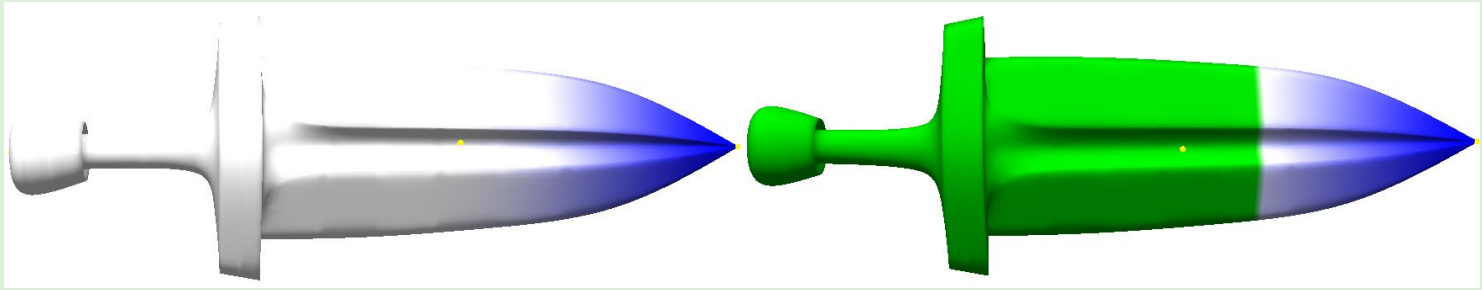


Handle	User Interaction													
	1	2	3	4	5	6	7	8	9	10	11	12	13	...
H_1	n	r	r					t	t	t	s	s		...
H_2	n			t	t	t	t				s	s		...
⋮	... ...													
H_m	n			t	t	t	t				s	s		...
H_{m+1}													n	...

Different types of manipulations

Weights Transmission

- Each handle's weights decay quickly so:
  - Send weights by TCP if greater than δ
  - Send weights by UDP if smaller than δ



plot of weights

plot of weight groups δ = 0.2

In a typical mesh editing system, each handle has the maximum effect on its immediate region and its influence disappears in distant parts of the object. We think that greater weights are important, should be translate by reliable channel, while the others by unreliable channel for system efficiency.

Weight Estimation

- Estimate lost weight

$$w_j(i) = \sum_{k \in \tilde{N}(i)} \mu_{ik} w_j(k)$$

- w_j : the weight function associated with handle H_j
- $\tilde{N}(i)$: the 1-ring neighbors of vertex v_i

$$m_{ik} = \frac{1}{|\tilde{N}(i)| - 1}\left(1 - \frac{\| v_i - v_k \|_2}{\sum_{l \in \tilde{N}(i)} \| v_i - v_l \|_2}\right)$$

$$\sum m_{ik} = 1$$

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Binding Time

Model	# of vertices	# of faces	Binding time per handle in different LODs 25%	50%	75%	100%
Heart	7349	14676	0.296	0.755	1.403	2.241
Sword	18001	35966	0.785	3.978	6.143	9.277
Dinosaur	56194	112384	3.446	11.167	19.681	30.193
Neptune	99996	200000	9.453	23.738	45.664	69.157

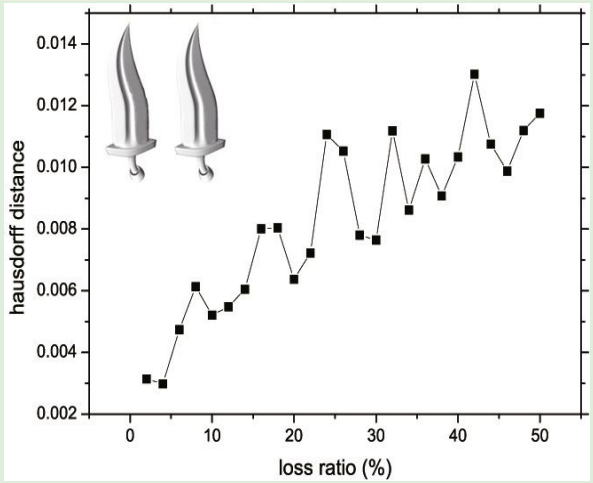
Statistics of binding time, measured in seconds.

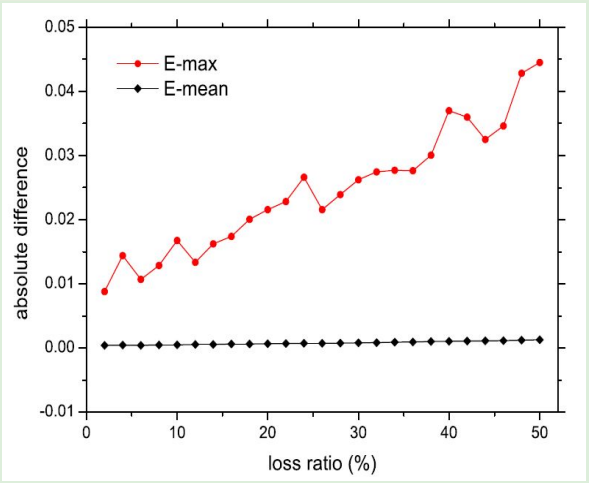
- The computational overhead of blending weights can be reduced significantly by using a simplified mesh.

Client:
- Core2 Duo Laptop
- 2.5GHz CPU
- 4GB RAM

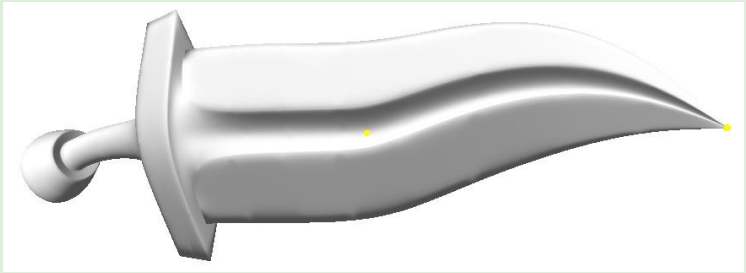
Server:
- Windows XP PC
- Intel Core2 Xeon 3.07GHz CPU
- 4GB RAM

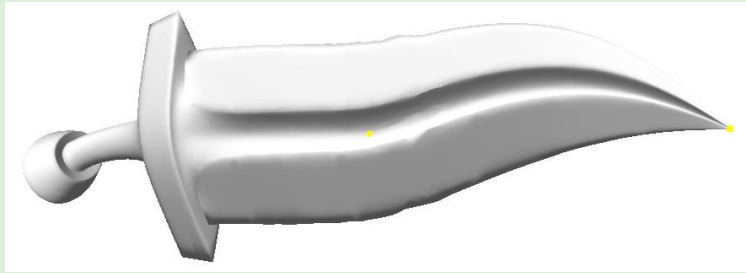
Weights Interpolation





The geometric distortion of the deformed Sword and weight interpolation error with different data loss ratios. The geometric distortion is measured in Hausdorff Distance.





δ = 0.2 and loss ratio is 50%

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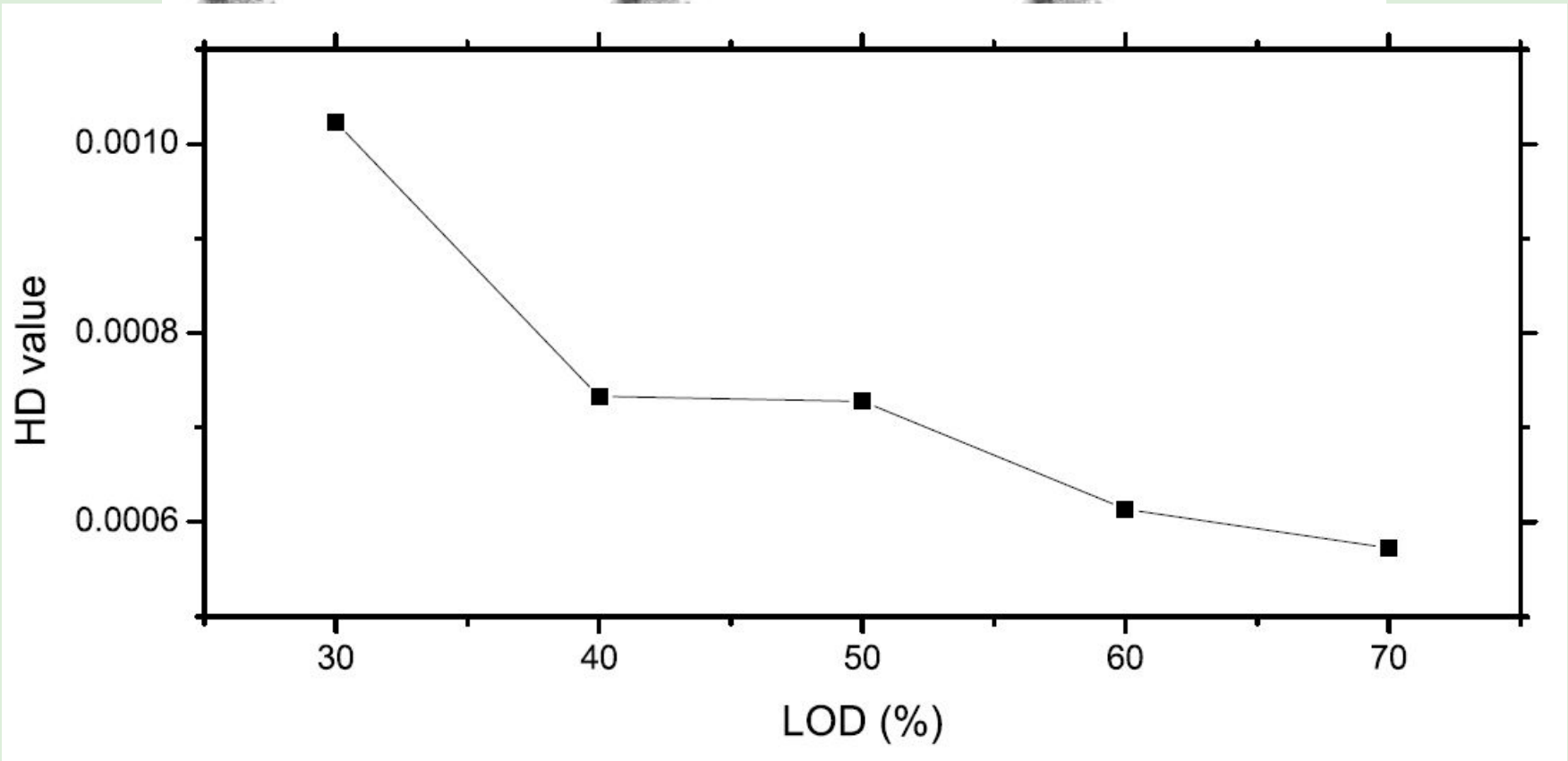
Simplified vs. Original Results



Simplified mesh results and the corresponding results by cloud server

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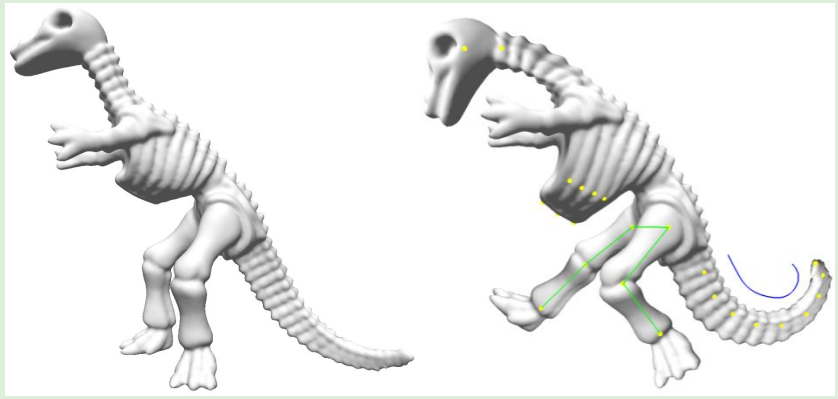
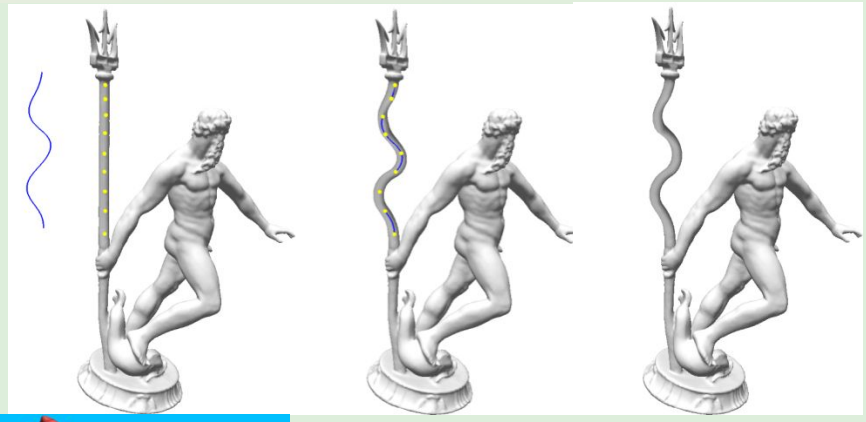
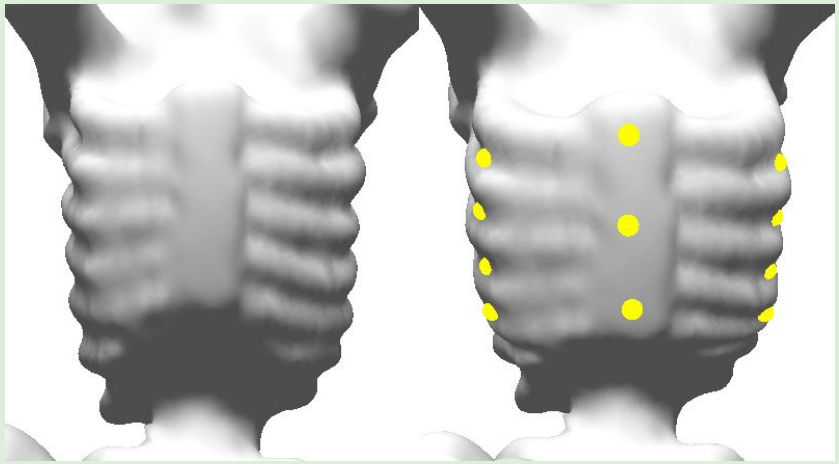
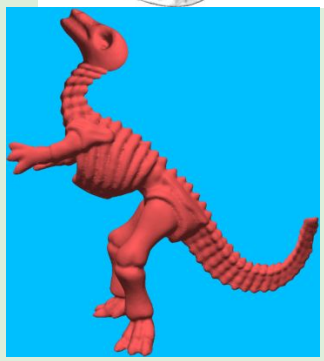
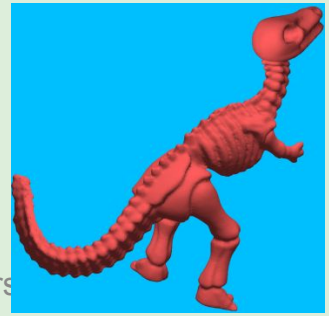
Examples

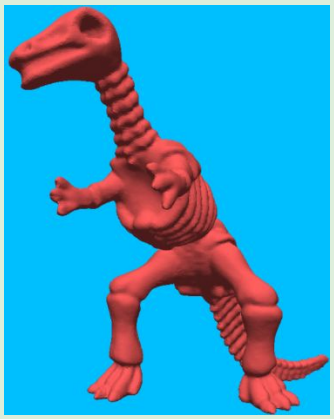


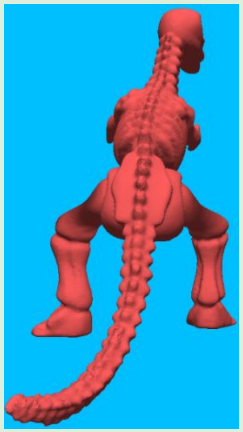












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Conclusion

- We have presented a system for cloud-based interactive mesh editing, namely GhostMesh.
- Allowing user to edit a complex mesh that stored in the cloud server by interactively modifying a simplified mesh locally.
- We proposed efficient strategies to classify and stream blending weights and user manipulations.

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Thank You